

Mathematical Aspects  
of  
Local vs. Global  
Risk Assessment

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Risk =

"known unknowns"

$\sim \mathcal{P}$

(Knightian)

Uncertainty =

"unknown unknowns"

$\sim$  model ambiguity

$\mathcal{P}$

a whole class of  
"plausible" probabilistic  
models

A case study:

the quantification of  
financial risk

— Beyond

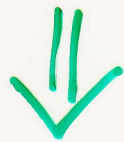
"Value at Risk"

$$\text{VaR}_\alpha(X) := \inf \{m \mid \underbrace{P[X+m < 0]}_{\text{criterion of acceptability}} \leq \alpha\}$$

↑  
financial  
position

$$X: \Omega \rightarrow \mathbb{R}$$

Axiomatic approach  
(what do we really want?)



theory of monetary  
(convex / coherent)  
risk measures

- initiated by  
Artzner, Delbaen, Eber, Heath (1999)
- extended by  
F. Schied, Frittelli, Rosazza-Giaquini (2002)

# Monetary Risk as a Capital Requirement:

(regulatory perspective,  
cf. Basel I, II, ...)

$$g(X) = \inf \{ m \mid X + m \in \mathcal{A} \}$$

↑  
"acceptable"  
positions

$\mathcal{A}$  saturated from above  
convex

(diversification is not  
penalized)



a convex risk measure

$$g: \mathcal{X} \rightarrow (-\infty, \infty]$$

"  
a linear space of measurable  
functions  $X$  on  $(\Omega, \mathcal{F})$   
"financial positions"

• monotone:

$$X \geq Y \Rightarrow g(X) \leq g(Y)$$

• cash-invariant:

$$g(X+m) = g(X) - m$$

• convex:

$$g(\alpha X + (1-\alpha)Y) \leq \alpha g(X) + (1-\alpha)g(Y)$$

("coherent": also pos. homogeneous,  
i.e.  $\mathcal{A}$  is convex cone  $\mathcal{Z}$ )

⇓ Feuchel - Floreau  
(+ some continuity)

robust / dual representation

$$g(x) = \sup_{Q \in \mathcal{Q}} \left( \underbrace{\mathbb{E}_Q[-x]}_{\text{expected loss under } Q} - \alpha(Q) \right)$$

where

$\mathcal{Q}$  = a class of probability measures on  $(\Omega, \mathcal{F})$

$$\alpha(Q) = \sup_{X \in \mathcal{X}} \mathbb{E}_Q[-X] \quad \text{"penalty"}$$

In general (beyond "law-invariance"): a case study in "Knightian uncertainty"

"law-invariance":

$g(X)$  depends on  
 $\mu_X :=$  law of  $X$  under  
given probability measure  
 $P$  on  $(\Omega, \mathcal{F})$

$\sim$  a functional  
 $R$  on "lotteries"

+ "elicitability"  
( $\Rightarrow$  convex level sets)

$\Rightarrow$

"shortfall risk  
measures"

S. Weber 2006  
(Gneiting, Fiegel)  
F. Delbaen

("expectiles")



utility-based  
shortfall risk (UBSR)

$X$  acceptable :  $\Leftrightarrow$

$$E_p[u(X)] \geq u_0$$

or

$$E_p[\ell(-X)] \leq \ell_0$$

$\ell(x) = -\ell(-x)$   
loss function

penalty function:

$$\alpha(Q) = \inf_{\lambda > 0} \frac{1}{\lambda} (\ell_0 + E_p[\ell^*(\lambda \frac{dQ}{dP})])$$

Example: "entropic" risk measure

$$u(x) = 1 - e^{-\beta x} \Rightarrow g(x) = \frac{1}{\beta} \log E_p[e^{-\beta x}]$$

$$\alpha(Q) = \frac{1}{\beta} H(Q/P)$$

from a mathematical  
point of view:

rich "prehistory"  
many interfaces

- Choquet integrals (50's)
- Actuarial premium principles  
Deprez, Gerber (1985)

$$\pi(X) = \rho(-X)$$

$\rho$  = convex risk measure

- Robust Statistics  
T. Huber (1981)  
~ coherent case

- Preferences in the face of Risk and Uncertainty

$$X \succeq Y$$

↔  
mild conditions  
(Debreu, Arrow-  
Milnor, ...)

$$U(X) \succeq U(Y)$$

i.e., numerical representation  
by some "utility  
functional"

von Neumann - Morgenstern,  
Savage, ... :

classical "axioms of rationality"



$$U(X) = E_P[u(X)]$$

for some

- utility function  $u$
- probability measure  $P$

paradigm of "expected utility"

more flexible

"axioms of rationality":

- Gilboa - Schmeidler (1989)
- Maccheroni, Marinacci, Rustichini (2006)



$$U(X) = - \rho(u(X))$$

convex \* risk measure

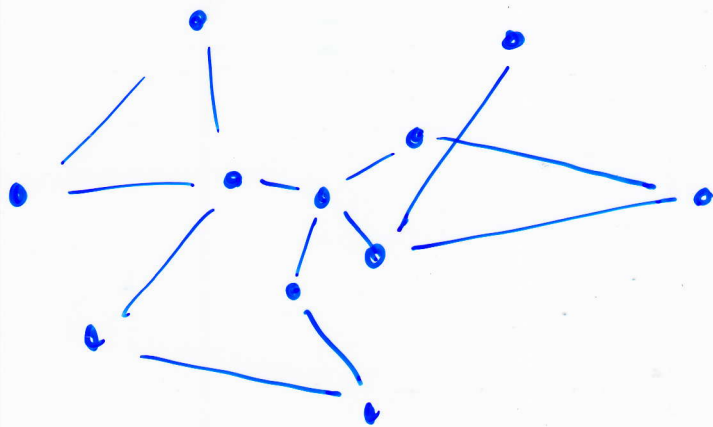
(Gilboa-Schmeidler: coherent)

$$= \inf_{Q \in \mathcal{Q}} \left( \mathbb{E}_Q [u(X)] + \alpha(Q) \right)$$

\* reflect model uncertainty aversion  
while concavity of  $u$  reflects  
classical risk aversion

local vs. global  
risk assessment  
in terms of convex risk measures

— in a large financial  
network



$I$  = set of "sites" / nodes  
 $S$  = set of possible states  
for each site (e.g.  $\mathbb{R}^d$ )

space of configurations:

$$\Omega := S^{\mathbb{I}} = \text{all } \omega: \mathbb{I} \rightarrow S$$

$$\bar{\mathcal{X}} := \text{all } \bar{X} = (X_i)_{i \in \mathbb{I}}$$

↑  
e.g.: P&L at  $i$

"systemic" risk measure

$\rho$  = a convex risk measure  
on  $\bar{\mathcal{X}}$  (Banach space  
e.g.  $(L^p)^{\mathbb{I}}$ )

typically:

"structural decomposition"

$$\bar{g} = g \circ \lambda$$

where

i)  $\lambda: \bar{\mathcal{E}} \rightarrow \mathcal{R}^1$   
is a real-valued concave  
"aggregation function"

ii)  $g$  is a "global"  
convex risk measure  
on  $\mathcal{X} \cong \lambda(\bar{\mathcal{E}})$

cf. Chen, Moallemi (2013)

Kromer, Overbeck, Zilch (2014)

---

a general structure theorem!

dual representation:

$$\bar{g}(\bar{x}) = g(+1(\bar{x}))$$

$$= \sup_Q \left( \mathbb{E}_Q \left[ \underbrace{-1(\bar{x})}_{\text{convex}} \right] - \alpha(Q) \right)$$

$$= \sup_{e'} (e', \bar{x}) - (-1)^*(e')$$

$$= \sup_{Q, e} \left( \mathbb{E}_Q [(e, \bar{x})] - \bar{\alpha}(Q, e) \right)$$

cf. Overbeck et al (2014)



more detailed  
financial picture ?

S. Weber, Z. Feinstein, B. Rudloff  
(2015 / Lectures Nov. 2014  
Isaac Newton Institute)

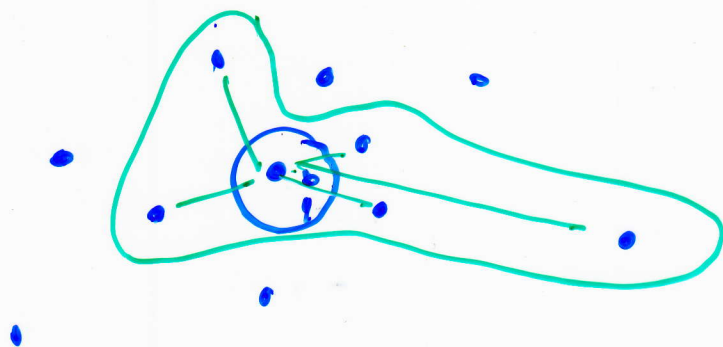
- specification / set-valued extension
- contains as special case

M. Brunnenmeier, P. Cheridito  
(2014)

"Measuring and allocating  
financial risk":

global  $\mathcal{S} = \text{UBSR}$

## Local risk assessment:



$N(i)$  = "neighbors" of  $i$

$$g_{\{i\}}(\omega, X_i)$$

= regular convex risk kernel  
from  $(\Omega, \mathcal{F}, \mathbb{I}-\mathcal{L}_i)$  to  $(\Omega, \mathcal{F})$

- assesses the risk at  $i$ ,  
conditional on the  
"environment" of  $i$

= situation on  $\mathbb{I}-\mathcal{L}_i$   
(or  $N(i)$ )

— conditional

(not marginal)

approach

cf. "CoVaR"

(Adrian, Brunnermeier)

more generally:

For any  $V \in \mathcal{D} :=$  all finite  $V \subseteq I$

$\rho_V(\omega, \cdot)$  = regular convex  
risk kernel  
from  $(\Omega, \mathcal{F}_V)$  to  $(\Omega, \mathcal{F})$

Definition: The family  $(\rho_V)_{V \in \mathcal{D}}$   
is called a local specification  
(of a convex risk measure) if  
it is spatially consistent,  
i.e.,

$$\rho_\omega = \rho_\omega(-\rho_V) \quad \forall V \subseteq \omega$$

or, equivalently:

$$\rho_V(\cdot, X) \geq \rho_V(\cdot, Y) \Rightarrow \\ \rho_\omega(\cdot, X) \geq \rho_\omega(\cdot, Y)$$

special "linear" case:

Gibbs measures

(Dobrushin, Lanford, Ruelle)

$$g_V(\omega, X) = \int -X(y) \pi_V(\omega, dy)$$

where

$(\pi_V)_{V \in \mathcal{D}}$  = local specification  
of a random field

i.e.,

•  $\pi_V(\omega, dy)$  is a stochastic kernel  
from  $(\Omega, \mathcal{F}_V)$  to  $(\Omega, \mathcal{F})$

•  $\pi_\omega \pi_V = \pi_\omega \quad \forall \omega \supseteq V$

(spatial consistency)

a non-linear example:

$$g_V(\omega, X) = \frac{1}{\beta} \log \int e^{-\beta X(y)} \pi_V(\omega, dy)$$

$$= \sup_{Q(\omega, \cdot) \approx \pi_V(\omega, \cdot)} \left( \mathbb{E}_{Q(\omega, \cdot)} [X] - \frac{1}{\beta} H(Q(\omega, \cdot) / \pi_V(\omega, \cdot)) \right)$$

— "entropic" local specification  
with parameter  $\beta \in [0, \infty)$

▷ the linear case

( $\beta = 0$ : limiting case)

$$g_V(\omega, X) = \int (-X) d\pi_V(\omega, \cdot)$$

## Problem I :

Construction of a local specification  $\{\rho_V \mid V \in \mathcal{O}\}$  from the one-site wise measures  $\{\rho_{\pm i} \mid i \in \mathbb{I}\}$

How arbitrarily can we prescribe the conditional wise measures at the single sites ?

"local consistency" ?

solution in the "linear" case  
(Dobrushin, Spitzer):

$(\pi_{\{i\}})_{i \in I}$  admits a consistent extension to a local specification

$(\pi_V)_{V \in \mathcal{D}} \iff$   
S discrete  
"Markov" w.r.t. graph structure

$\exists$  "interaction potential"

$(U_C)_{C \in \mathcal{C}} :=$  the cliques of the graph  
 $\mathcal{F}_C$ -measurable

$$\pi_{\{i\}}(\omega, s) \sim \exp \left( \sum_{\substack{C \in \mathcal{C} \\ i \in C}} U_C(\omega_{\{i\}^c}, s) \right)$$



In the non-linear case :

- wide open in general
- solved in the "locally law-invariant" case  
(cf. below)

## Problem II:

Given a local specification

$$(\mathcal{S}_V)_{V \in \mathcal{D}},$$

what is the structure of

$\mathcal{Q} :=$  all global convex  
risk measures  $\mathcal{Q}$   
such that

$$\mathcal{Q}(-\mathcal{S}_V) = \mathcal{Q} \quad \forall V \in \mathcal{D}$$

?

- uniqueness vs. "phase transition"
- $\sim$  integral representation  
(cf. Gibbs measures)

solution in the "linear" case of  
Gibbs measures:

$\mathcal{P} :=$  all  $\mathcal{P}$  on  $(\Omega, \mathcal{F})$   
consistent with  $(\pi_V)_{V \in \mathcal{O}}$ ,  
i.e.,  $\mathcal{P} \pi_V = \mathcal{P} \quad \forall V \in \mathcal{O}$

"phase transition" :  $\Leftrightarrow |\mathcal{P}| > 1$

non-uniqueness

structure of  $\mathcal{P}$ :

$\mathcal{P}_e := \left\{ \mathcal{P} \in \mathcal{P} \mid \mathcal{P} = 0-1 \text{ on } \mathcal{F}_\infty \text{ "ergodic"} \right\}$

where

$\mathcal{F}_\infty := \bigcap_{V \in \mathcal{O}} \mathcal{F}_{V^c}$   
"tail field"

integral representation  
coupled to the tail field

- adapting Dynkin's construction  
of entrance boundaries for  
Markov processes:

$\exists$  stochastic kernel  $\pi_\infty$   
from  $(\Omega, \mathcal{F}_\infty)$  to  $(\Omega, \mathcal{F})$ :

$$i) \quad \pi_\infty(\omega, \cdot) \in \mathcal{P}_e \quad \forall \omega \in \Omega$$

$$ii) \quad P = P \pi_\infty \quad \forall P \in \mathcal{P}$$

i.e.

$$\begin{aligned} P &= \int \pi_\infty(\omega, \cdot) P|_{\mathcal{F}_\infty} (d\omega) \\ &= \int_{\mathcal{P}_e} Q \mu_P(dQ) \end{aligned}$$

cf. F., "Phase transition and Martin  
Boundary" (1975)

essential part  
(in analogy to "Martin boundary"):

$$(\Omega, \mathcal{F}^1) = \underline{\text{"Dyckin Boundary"}}$$

where

$$\mathcal{F}^1 := \sigma \left( \begin{array}{l} \omega \rightarrow \pi_\infty(\omega, \cdot) \\ \Omega \rightarrow \mathcal{P}_e \end{array} \right)$$

Thus:

Gibbs measures  $\mathcal{P} \in \mathcal{P}$

$\longleftrightarrow$   
1-1

probability measures  
on Dyckin Boundary

analogue in the  
"non-linear" case of

risk measures

$\rho \in \mathcal{R}$  ?

A) solved in the case of  
local law-invariance :

$\rho_V(\omega, \cdot)$  law-invariant w.r.t.  
 $\pi_V(\omega, \cdot)$

A.F., Statistics and Risk Modeling  
(2014)

B) general case

$\rho_V(\omega, \cdot) \ll \pi_V(\omega, \cdot)$

A.F., C. Klüppelberg

## Excursion:

a general result on  
consistency & law-invariance

cf. Kupper, Schachermayer (2009)  
Cerrica-Voglio, Maccheroni,  
Marinacci, Montucchio (2011)  
- with a new twist

$\rho$  = "nice" law-invariant risk  
measure on  $L^\infty(\Omega, \mathcal{F}, P)$   
atomless

↓  
partial order on "lotteries", i.e.,  
on  $\mathcal{M}_f(\mathbb{R}^1)$ :

$$\mu \succeq \nu \iff \rho(X) \leq \rho(Y)$$

where  $\text{Law}(X) = \mu$ ,  $\text{Law}(Y) = \nu$

i.e.

$$\mu \succeq \nu \iff C(\mu) \succeq C(\nu)$$

$$C(\mu) := -f(x)$$

We know:

If  $\succeq$  satisfies the von Neumann-Morgenstern axioms then

$\exists v \uparrow$  continuous:

$$\mu \succeq \nu \iff \int v d\mu \geq \int v d\nu$$

"expected utility"



$$C(\mu) = v^{-1}(\int v d\mu)$$

"certainty equivalent"



But:

$C(\cdot)$  = certainty equivalent  
w.r.t.  $u$   
+ cash-invariant, i.e.,  
 $C(\mu \text{ shifted by } m) = C(\mu) + m$



de Finetti:  
Sul concetto di media  
(1931)

(cf. FS, 3<sup>rd</sup> ed., Prop. 2.46)

$u$  exponential ( $\cong$  linear)

i.e.

$\rho$  = entropic risk measure

crucial condition:

"independence axiom"

$\mu \succeq \nu$ ,  $\lambda \in (0,1)$ ,  $\forall$  lottery  $\gamma$ :

$$\lambda\mu + (1-\lambda)\gamma \succeq \lambda\nu + (1-\lambda)\gamma$$

— follows from consistency!

More precisely:

for  $\mathcal{F}_0 \subseteq \mathcal{F}$ ,  $g$  is called  $\mathcal{F}_0$ -consistent if

$$g = g(-g_0)$$

for some conditional v.s.d. measure  $g_0$  w.r.t.  $\mathcal{F}_0$

In particular:

$$g_0(XI_{A_0} + YI_{A_0^c}) = g_0(X)I_{A_0} + g_0(Y)I_{A_0^c}$$

("locality")

Theorem: Suppose that the law-invariant vis $\Sigma$  measure  $g$  is  $\mathcal{F}_0$ -consistent for some  $\mathcal{F}_0$  such that

i)  $(\Omega, \mathcal{F}_0, \mathcal{P})$  is atomless

ii)  $(\Omega, \mathcal{F}, \mathcal{P})$  is conditionally atomless given  $\mathcal{F}_0$

( $\exists U_1, U_2, \dots$  i.i.d. uniform,  $\perp \mathcal{F}_0$ )

Then

$g$  is entropic

(hence "fully consistent", i.e.,  $\mathcal{F}_1$ -consistent  $\forall \mathcal{F}_1 \subseteq \mathcal{F}$ )

Proof: Check the independence axiom:  
 (C-V, A1, A2, A3 + conditional twist)

$\mu, \nu, \gamma, \lambda \in (0, 1), \mu \succeq \nu$

To show:

$$\lambda\mu + (1-\lambda)\gamma \succeq \lambda\nu + (1-\lambda)\gamma$$

$$\exists X, Y, Z \sim \mu, \nu, \gamma, \perp \mathcal{F}_0$$

$$A_0 \in \mathcal{F}_0: P[A_0] = \lambda$$

$$\Rightarrow \begin{aligned} \lambda\mu + (1-\lambda)\gamma &\sim \mathbb{I}_{A_0} X + \mathbb{I}_{A_0^c} Z \\ \lambda\nu + (1-\lambda)\gamma &\sim \mathbb{I}_{A_0} Y + \mathbb{I}_{A_0^c} Z \end{aligned}$$

Thus:

$$C(\lambda\mu + (1-\lambda)\gamma) = -\rho(\mathbb{I}_{A_0} X + \mathbb{I}_{A_0^c} Z)$$

$$\begin{aligned} \text{to show: } &\geq C(\lambda\nu + (1-\lambda)\gamma) \\ &= -\rho(\mathbb{I}_{A_0} Y + \mathbb{I}_{A_0^c} Z) \end{aligned}$$

Indeed:

$$g(XI_{A_0} + ZI_{A_0^c})$$

= consistent  $g(\underbrace{g_0(XI_{A_0} + ZI_{A_0^c})}_{\text{locality}})$

$$\begin{aligned} &= \underbrace{I_{A_0} g_0(X)}_{\text{locality}} + \underbrace{I_{A_0^c} g_0(Z)}_{\text{locality}} \\ &= \underbrace{g(X)}_{X \perp \mathcal{F}_0} + \underbrace{g(Z)}_{Z \perp \mathcal{F}_0} \end{aligned}$$

$$\leq_{\mu \succeq \nu} g(Y)$$

hence

$$g(XI_{A_0} + ZI_{A_0^c}) \leq_{\text{monotone}} g(YI_{A_0} + ZI_{A_0^c})$$

i.e.

$$\lambda \mu + (1-\lambda) \gamma \succeq \lambda \nu + (1-\lambda) \gamma$$

q.e.d.

Corollary (Kupper-Schacher-mayer):

Law-invariant and  
dynamically consistent  
convex vix measures are  
entropic

here:

alternative "static" proof

- without auxiliary Markov chain/  
Skorohod's embedding principle  
(does not work in spatial setting)

Back to our

spatial setting:

Given:

$$i) (\pi_V)_{V \in \mathcal{D}}$$

= local specification of a  
random field  
(à la Dobrushin)

$$ii) (\rho_V)_{V \in \mathcal{D}}$$

= local specification of a  
convex risk measure

— tied to  $(\pi_V)_{V \in \mathcal{D}}$ :

A) local law-invariance:

$g_V(\omega, \cdot)$  is law-invariant w.r.t.  
 $\pi_V(\omega, \cdot)$

+ consistency  $g_W - g_V = g_\omega$

$\Rightarrow$  locally entropic:  
Theorem

$$g_V(\omega, X) = \frac{1}{\beta_V(\omega)} \log \int e^{-\beta_V(\omega) X(y)} \pi_V(\omega, dy)$$

Due to consistency:

$$\begin{aligned} \beta_V(\omega) &= \beta_\omega(\omega) & \mathbb{P}\text{-a.s. } \forall \mathbb{P} \in \mathcal{P} \\ &= : \beta_\infty(\omega) \end{aligned}$$

tail-measurable



In this case:

straightforward consistent  
extension of  $(\mathcal{G}_V)$  to  
the tail field:

$$\mathcal{G}_\infty(\omega, X) = \frac{1}{\beta_\infty(\omega)} \log \int_{\infty} e^{-\beta_\infty(\omega) X(y)} \pi_\infty(\omega, dy)$$

Dynkin's kernel

= key to structure problem (II)  
(cf. general case below)

B) Beyond (local) Law-invariance:

Assume only:

$$g_V(\omega, \cdot) \ll \pi_V(\omega, \cdot)$$

i.e.

$$g_V(\omega, X) = g_V(\omega, Y) \quad \text{if } X = Y \text{ and } \pi_V(\omega, \cdot) \text{ - a.s.}$$

$\Rightarrow$   
DeLafayette-  
Scandolo

$$\forall P \in \mathcal{P} :$$

$$g_V(\cdot, X) = \text{ess. sup}_{Q \ll P} \left( \mathbb{E}_Q [X | \mathcal{F}_{Vc}] - \alpha_V(Q) \right)$$

$Q \approx P \text{ on } \mathcal{F}_{Vc}$

extension to

tail field  $\mathcal{F}_\infty = \bigcap \mathcal{F}_{Vc} ?$

trivial extension:

Fix  $V_n \uparrow I$ ,  $\mathbb{F}_{V_n} \downarrow \mathbb{F}_\infty$ .  
Define

$$g_\infty(\omega, X) := \overline{\lim}_n g_{V_n}(\omega, X)$$

- a regular convex risk kernel  
from  $(\Omega, \mathbb{F}_\infty)$  to  $(\Omega, \mathbb{F})$

- consistent with  $(g_V)_{V \in \mathcal{D}}$   
i.e.

$$g_\infty(-g_V) = g_\infty$$

properties under PEP?

- via non-linear extension of  
backwards martingale convergence:

Fix  $V_n \in \mathcal{V}$ ,  $V_n \uparrow I$ ,  $\mathcal{F}_{V_n^c} \downarrow \mathcal{F}_\infty$

Consistency along  $(\mathcal{F}_{V_n^c})$

$\Rightarrow$

Delbaen, Kupper, Cheridito  
Biau-Nadal  
F., Penner

$\forall P \in \mathcal{P}$ :

$$V_n(P, X) := g_{V_n}(X) + \alpha_{V_n}(P) \\ (n=1, 2, \dots)$$

backwards supermartingale  
w.r.t.  $P$  along  $(\mathcal{F}_{V_n^c})$ ,  
hence

convergent  $P$ -a.s.

ie:  $P$ -a.s.  $\forall P \in \mathcal{P}$

Proposition (F., Irina Penuer):

$\forall P \in \mathcal{P}$

- $g_{\infty}(x) = \lim_n g_{V_n}(x)$  P-ans.  
for any  $x \in \mathcal{H}$
- $g_{\infty}$  has Fatou property  
w.r.t.  $P$
- dual representation with  
penalty function  
$$\alpha_{\infty}(Q) = \lim_n \alpha_{V_n}(Q)$$
  
P-ans.

---

key to structure problem (II)

# regularization:

$$\hat{P}_\infty(\omega, X) := \int P_\infty(y, X) \pi_\infty(\omega, dy)$$

- a regular convex visé kernel from Dynkin boundary  $(\Omega, \hat{\mathcal{F}})$  to  $(\Omega, \mathcal{F})$
- consistent with  $(S_\nu)_{\nu \in \mathbb{N}}$
- $\hat{P}_\infty(\omega, \cdot)$  has Fatou property w.r.t.  $\pi_\infty(\omega, \cdot)$
- $\hat{P}_\infty(\cdot, X) = P_\infty(\cdot, X)$   
 $\pi_\infty(\omega, \cdot)$ -a.s.  $\forall \omega \in \Omega$   
(by ergodicity),  
hence  $\mathbb{P}$ -a.s.

$\mathcal{R}_L =$  all global v.s.d measures  
 $\mathcal{g} \in \mathcal{Q}$  which have the  
Lebesgue property  
w.r.t.  $\mathcal{P}$ , i.e.,

$$\mathcal{g}(X_n) \rightarrow \mathcal{g}(X)$$

for any uniformly bounded sequence  
 $(X_n) \subseteq \mathcal{H}$  such that

$$\lim_n X_n = X \quad \mathcal{P}\text{-a.s.}$$

$$\hat{\mathcal{R}}_L = \text{all } \mathcal{g} \in \hat{\mathcal{Q}}$$

(convex v.s.d measures  
on the Dynkin boundary,  
i.e. on  $\hat{\mathcal{M}} := \mathcal{M}_b(\Omega, \hat{\mathcal{F}})$ )

with Lebesgue property w.r.t.  $\mathcal{P}$   
(i.e., w.r.t. pointwise convergence)

Theorem. Any  $g \in \mathcal{R}_L$   
has the form

$$g = \hat{g}^1(-\hat{g}_\infty^1)$$

with some  $\hat{g}^1 \in \hat{\mathcal{R}}_L$ , namely

$\hat{g}^1 := g|_{\hat{M}}$  = restriction of  $g$   
to the Dynkin boundary

Proof.  $g \in \mathcal{R} \Rightarrow$

$$g(-\underbrace{g_{\nu_n}(x)}_{\in \hat{M}}) = g(x)$$

$$\xrightarrow{\text{P.-a.s.}} g_{\nu_n}(x) = \hat{g}_{\nu_n}^1(x)$$

$$\xrightarrow{g \in \mathcal{R}_L} g(-\underbrace{\hat{g}_\infty^1(x)}_{\in \hat{M}}) = \hat{g}^1(-\hat{g}_\infty^1(x))$$



Corollary. If each  $\hat{g}_\infty^\uparrow(\omega, \cdot)$  has Lebesgue property a.s. w.r.t.  $\pi_\infty(\omega, \cdot)$  (as in entropic case!) then

$$\mathcal{Q}_L = \left\{ \hat{g}^\uparrow(-\hat{g}_\infty^\uparrow) \mid \hat{g}^\uparrow \in \mathcal{Q}_L^\uparrow \right\}$$

on the Dyukin boundary

Proof. " $\Leftarrow$ ": ✓

" $\Rightarrow$ ":  $\hat{g}^\uparrow \in \mathcal{Q}_L^\uparrow \Rightarrow g := \hat{g}^\uparrow(-\hat{g}_\infty^\uparrow) \in \mathcal{Q}$

Lebesgue property:

$X_n \rightarrow X$   $\mathcal{P}$ -a.s.  $\Rightarrow \pi_\infty(\omega, \cdot)$ -a.s.  $\forall \omega \in \Omega$

$\Rightarrow$  Assumption  $\hat{g}_\infty^\uparrow(\omega, X_n) \rightarrow \hat{g}_\infty^\uparrow(\omega, X)$

$\Rightarrow g(X_n) = \hat{g}_\infty^\uparrow(-\hat{g}_\infty^\uparrow(\cdot, X_n))$   
 $\hat{g}^\uparrow \in \mathcal{Q}_L^\uparrow \Rightarrow \hat{g}_\infty^\uparrow(-\hat{g}_\infty^\uparrow(\cdot, X)) = g(X)$

In this case:

Corollary.

$$|\mathcal{Q}_L| = 1 \iff |\mathcal{P}| = 1$$

i.e., a global risk measure  $\rho \in \mathcal{Q}_L$  is uniquely determined by the local specification if and only if there is no probabilistic phase transition

Proof. 1)  $|\mathcal{P}| = 1 \Rightarrow \hat{\mathcal{F}}$  trivial  
 $\hat{K} = \text{the constants}$   
 $\hat{g}(m) = -m$   
unique

2)  $|\mathcal{P}| > 1 \Rightarrow \pi_\infty(\omega_1, \cdot) \neq \pi_\infty(\omega_2, \cdot)$   
 $\Rightarrow \hat{\rho}_\infty(\omega_i, \cdot) \ll \pi_\infty(\omega_i, \cdot) \perp$  (ergodicity)  
are different  $\Rightarrow |\mathcal{Q}_L| > 1$

However:

$$\underbrace{|\mathcal{P}| = 1} \quad \not\Rightarrow \quad |\mathcal{Q}| = 1$$

no probabilistic  
phase transition

i.e.

multiplicity of  
global v.s.d measures  
in  $\mathcal{Q}$  (without Lebesgue  
property)

— illustrated in  
entropic case:

entropic case:

$$g_{\infty}^1(\omega, X) = \frac{1}{\hat{\beta}(\omega)} \log \int e^{-\hat{\beta}(\omega) X(y)} \pi_{\infty}^1(\omega, dy)$$

$$\hat{\beta}(\omega) := \int \beta_{\infty}(y) \pi_{\infty}^1(\omega, dy)$$

$\hat{\beta}$  - measurable

$$|\mathcal{P}| = 1 \Rightarrow \begin{aligned} \pi_{\infty}^1(\omega, \cdot) &\equiv \mathcal{P} \\ \hat{\beta}(\omega) &\equiv \beta \end{aligned}$$

i.e., there is only one  $g \in \mathcal{R}_L$ ,  
namely the entropic risk measure  
w.r.t.  $\mathcal{P}$  and  $\beta$

But:

$$\begin{aligned} g_{\infty}(\omega, X) &:= \overline{\lim}_n g_{V_n}(\omega, X) \in \mathcal{R} \\ &= -X(\omega) \quad \forall \text{ tail-measurable } X \end{aligned}$$

i.e.

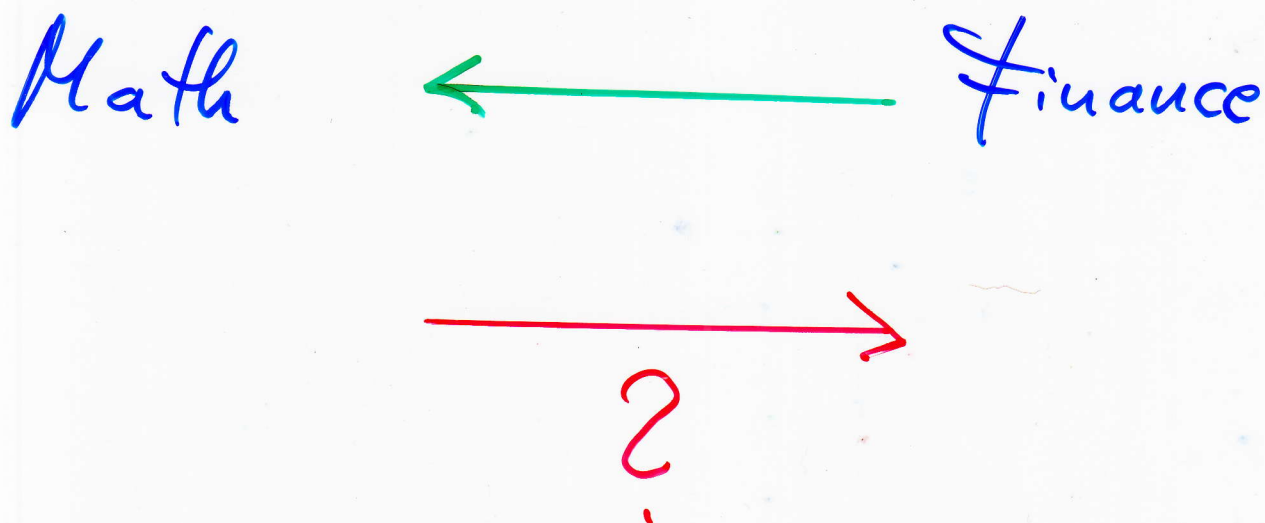
multiplicity in  $\mathcal{R}$ !

we have solved

## Problem (II)

= a purely mathematical structure problem somehow motivated by the much broader issue of risk analysis ("systemic risk") in large financial networks

- an example for



possible message:

local

(even conditional,  
vs. just marginal)  
risk analysis

may not suffice to capture  
all sources of the

aggregate

/"systemic" risk

- in non-linear analogy  
to the probabilistic analysis  
of phase transitions

Second message:

The consistency requirement  
is too strong  
(even though it seems  
plausible at first sight)

open problem:

What happens in the  
spatial setting, if we  
use related notions  
of consistency ?

(S. Weber 2006, S. Futschek 2007)

Thanks

for listening !